CERIAS

The Center for Education and Research in Information Assurance and Security



A Cybersecurity Testbed for Connected and Autonomous Vehicle Systems

Zengxiang Lei¹, Ruichen Tan¹, Satish V. Ukkusuri¹ ¹ Lyles School of Civil Engineering, Purdue University



Urban Mobility, Networks and Intelligence Lab

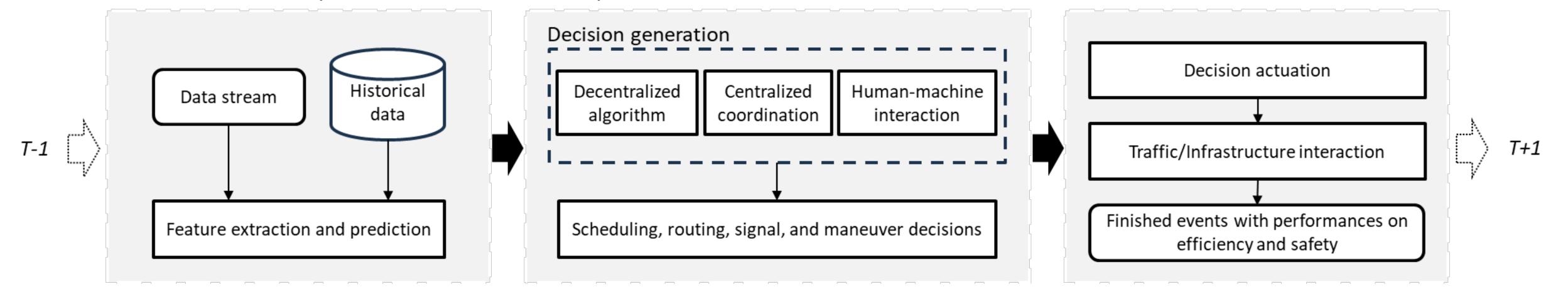
Overview

- The Transportation Cybersecurity and Resilience Center (TraCR) is developing a cybersecurity testbed for connected and autonomous vehicle (CAV) systems.
- The goal of this testbed is to comprehensively evaluate the impact of cyberattacks on CAV systems and assess the efficacy of defense algorithms.
- To achieve this, the testbed incorporates the full life cycles of transportation services (including private vehicles, ride-hailing, and public transit) with realistic data streams.

Information to Feature/Prediction

Feature/Prediction to Decision

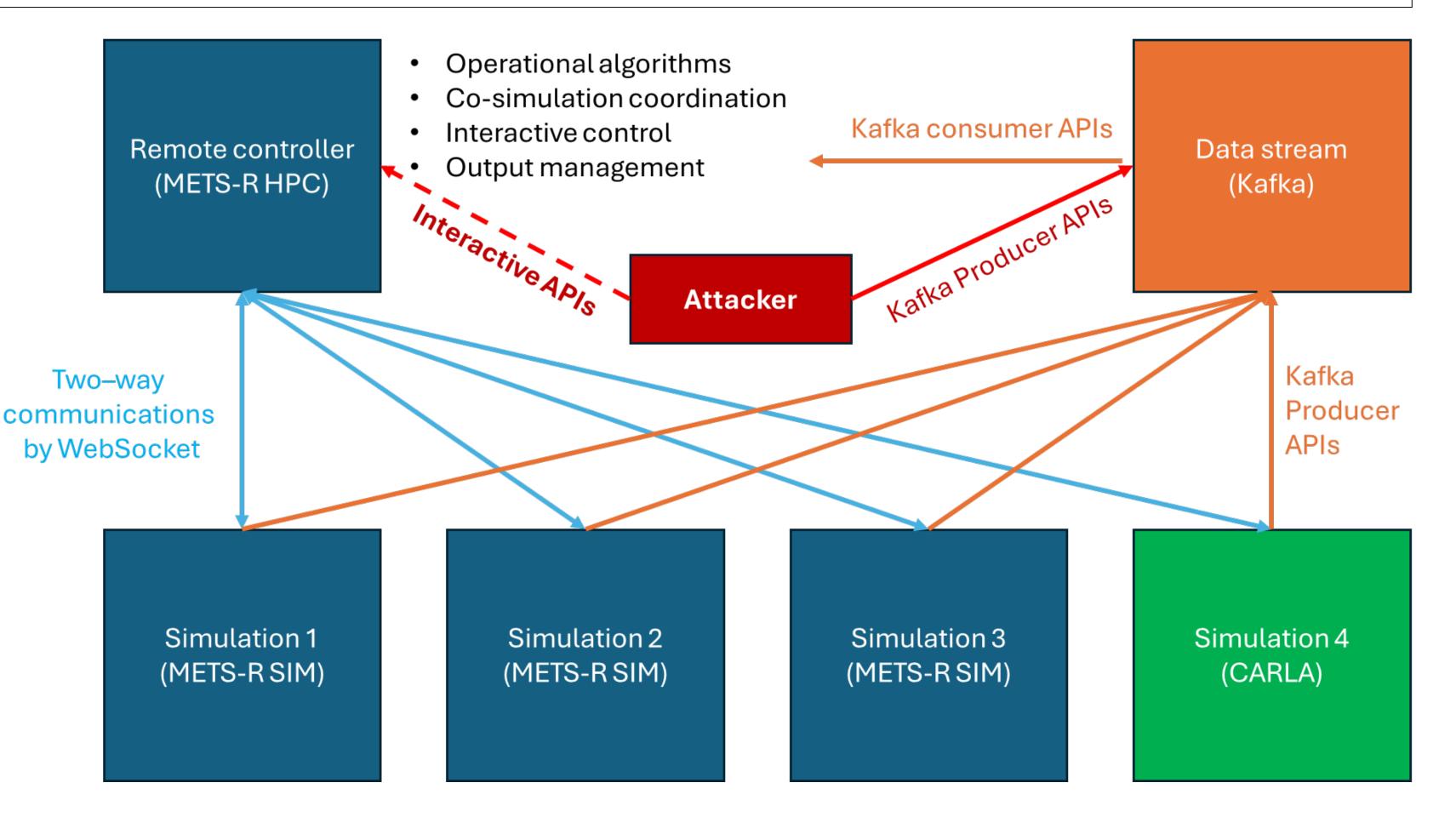
Decision to Performance



This poster shows the testbed design and current development progress.

Testbed design

- Our framework comprises three key components: simulator, data stream, controller.
- **Simulator**: We use METS-R SIM for large-scale multi-modal traffic simulation and CARLA for photorealistic sensor and driving simulation. This combination ensures comprehensive testing environments.
- **Data Stream**: This Kafka-based component can model the data stream explicitly and expose it to potential attacks like DoS and data spoofing. This also allows us to separate the logics of data processing, decision generation, traffic simulation, and attacks.
- **Controller**: The controller serves as the intermediary between multiple simulation instances and the data stream, this framework guarantees strict synchronization. By broadcasting simulation time among the simulator, data processor, and attacker, it enables sensible testing of attack algorithms with any level of computational costs.



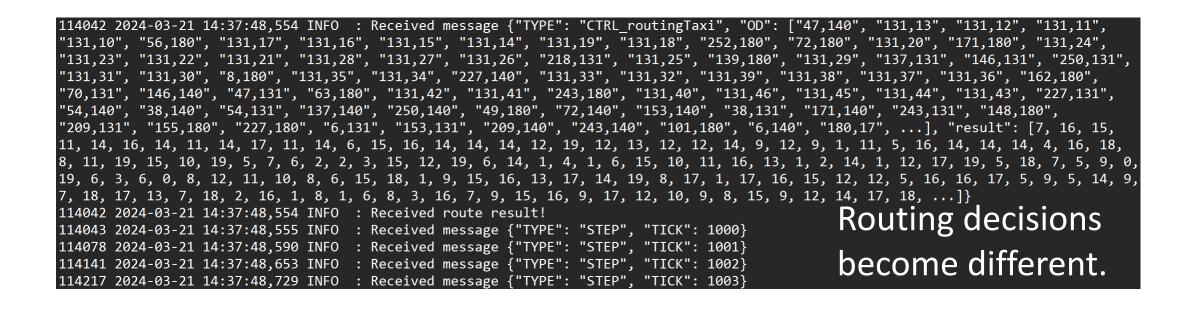
• Open source:

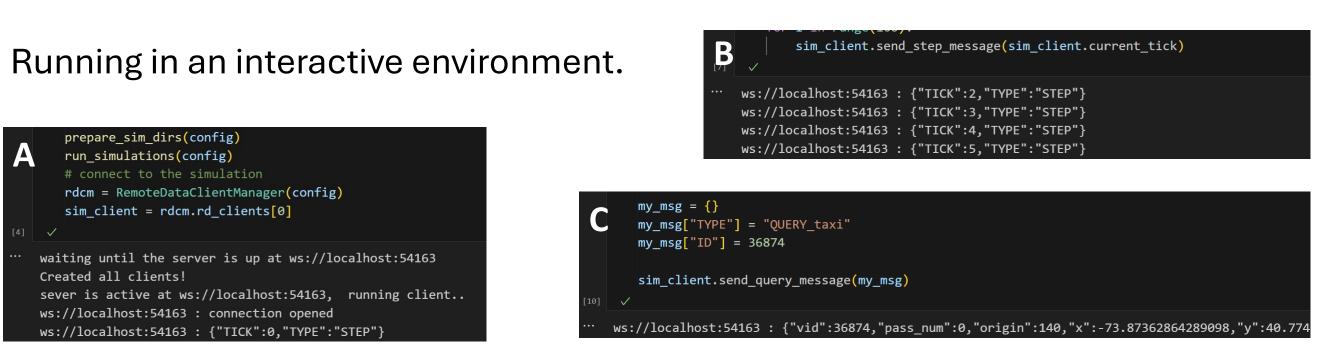
METS-R SIM: <u>https://github.com/umnilab/METS-R_SIM.git</u> METS-R HPC: <u>https://github.com/umnilab/METS-R_HPC.git</u> Visualization: <u>https://engineering.purdue.edu/HSEES/METSRVis/</u>

Use case examples

Testing attacks against the online routing algorithm for CAVs.

<pre>ws://localhost:53605 : {"TICK":276,"TYPE":"STEP"} {}</pre>	The attacker fabricates the link travel
ws://localhost:53605 : {"TICK":277,"TYPE":"STEP"}	The allacker fabricates the link traver
<pre>{} ws://localhost:53605 : {"TICK":278,"TYPE":"STEP"} {}</pre>	time and energy consumption data.
<pre>ws://localhost:53605 : {"TICK":279,"TYPE":"STEP"}</pre>	
	umerRecord(topic='link_energy', partition=0, offset=32591, timestamp=1711632536460, time _time': 275.0, 'veh_type': 1, 'link_energy': 0.10931387238947775, 'road_id': 107151}, he
<pre>ers=[], checksum=None, serialized_key_size=10, serialize</pre>	
ws://localhost:53605 : {"TICK":280,"TYPE":"STEP"}	





What's next?

- Currently, we are working on developing an extensive set of APIs for query/control the simulators.
- The next step is to leverage the platform to test typical attacks (e.g., GPS spoofing) against CAV systems and applications.



